



Subsurface Wave Measurements

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Overview of Presentation

- **Background on bottom mounted wave instruments**
- **AWAC**
- **AST**
- **SUV**
- **Malaga case study: Breakwater reflection**
- **Online applications**

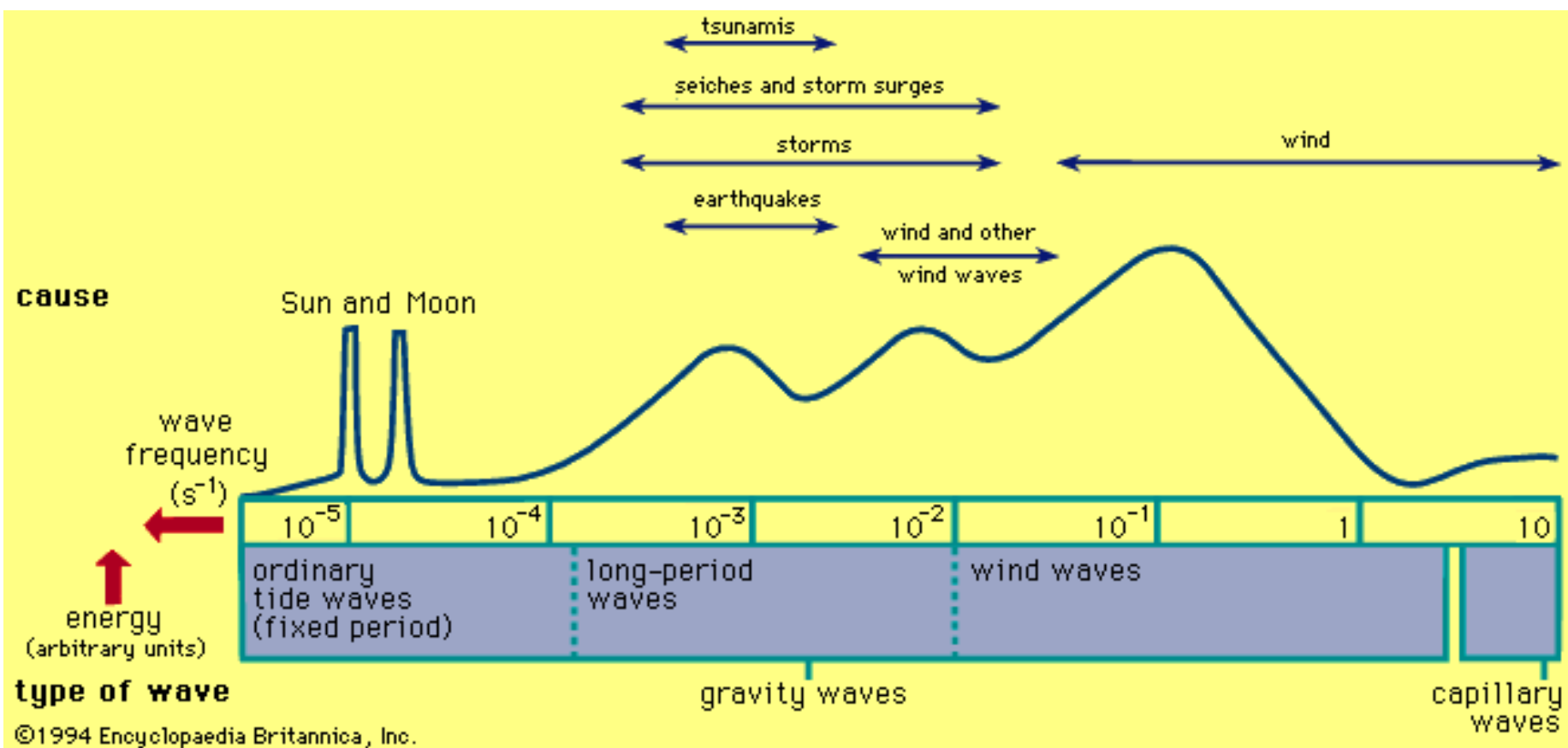


Assumptions...

- **Understanding on Doppler principle**
- **Doppler profilers**
- **Basic wave measurement concepts and standard data products such as Hieght, period and directional estimates**

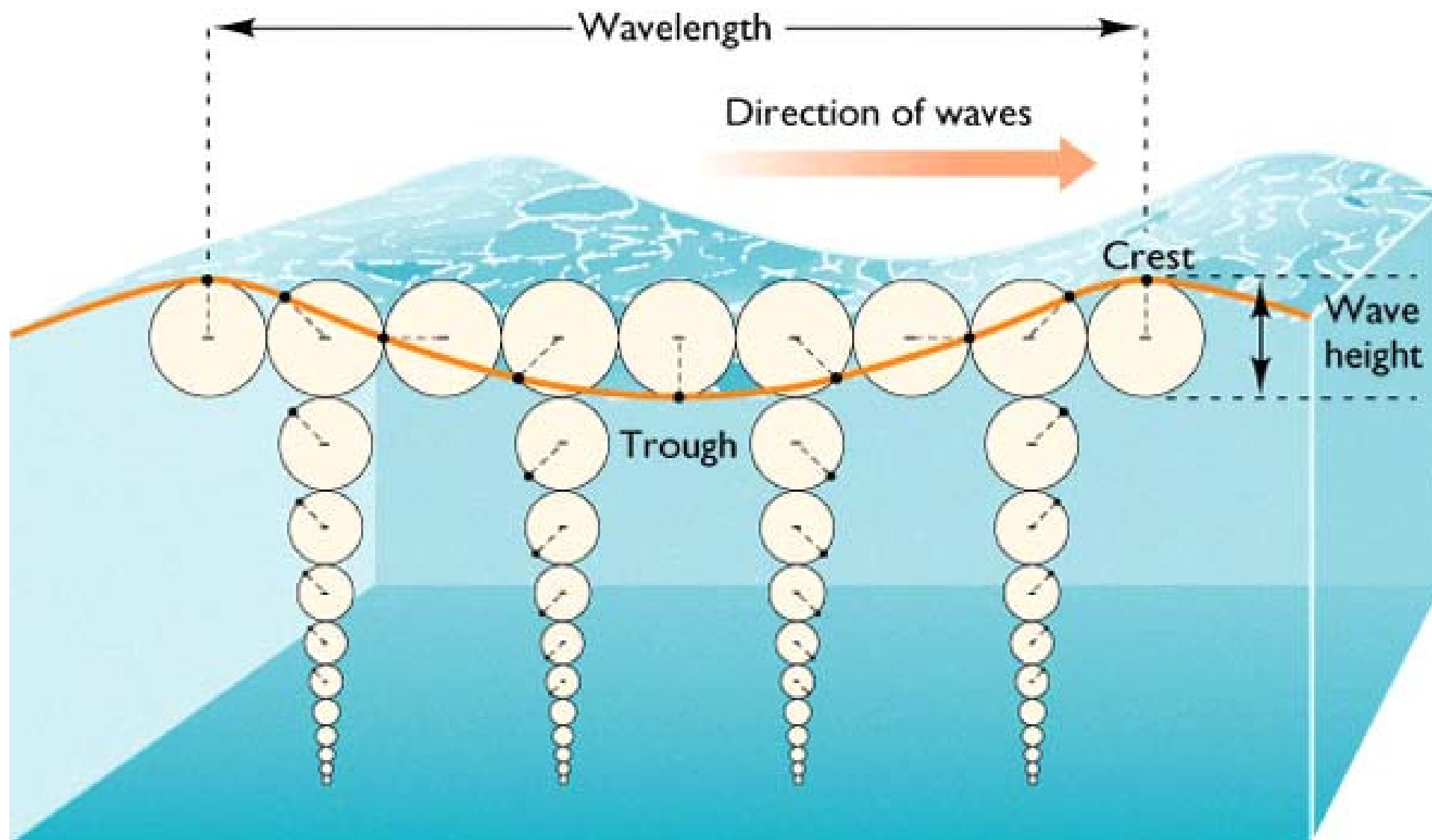


Wave Energy Distribution





Attenuation of wave properties





Orbital Velocity Animation

[Link to Orbital Velocity Animation](#)



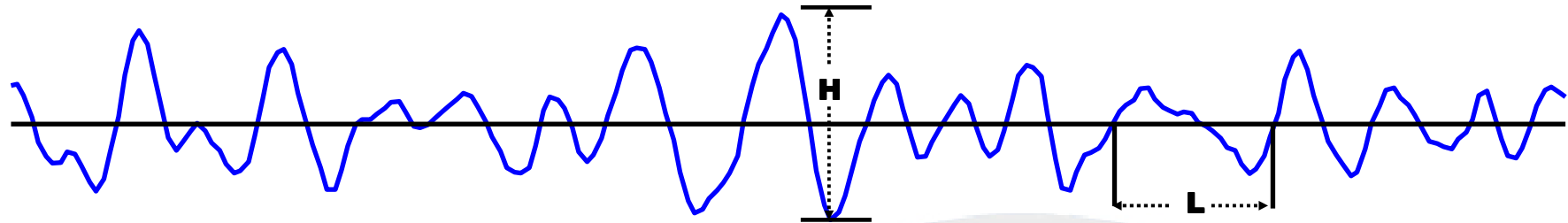


Data Products





Wave Estimates

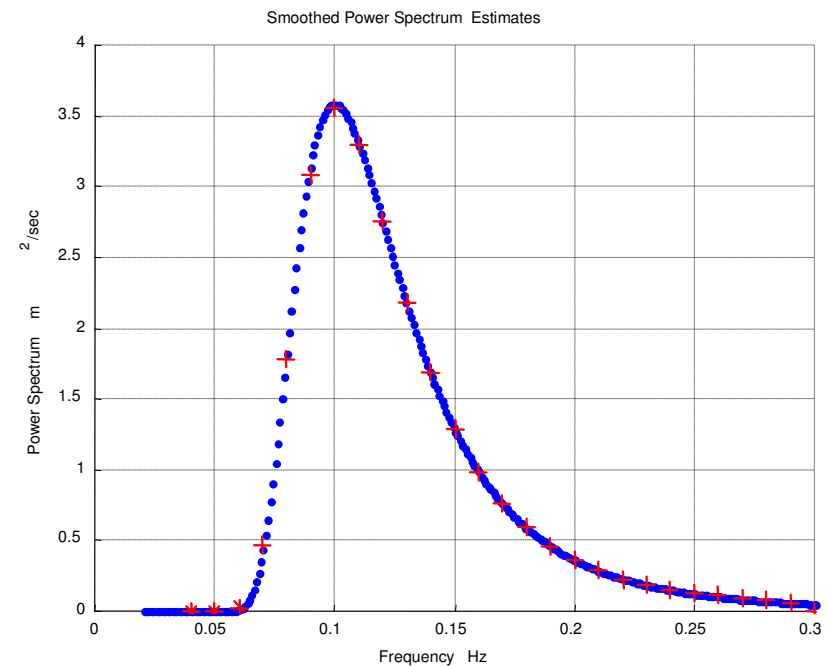


- H_s Significant Wave Height is the “mean of the 1/3 largest waves in a record”. Requires time series to estimates this directly

- Spectral alternative

$$H_s = 4\sqrt{m_0}$$

$$m_k = \int f^k S(f) df$$





Directional Distribution

$$E(f, \theta) = S(f)D(f, \theta)$$

Two dimensional Energy
Distribution

Where D can be considered a probability distribution over
Direction

$$\int_0^{2\pi} D(f, \theta) d\theta = 1$$

Criteria Directional Distribution
must fulfill

$$D(f, \theta) > 0$$



Directional Distribution

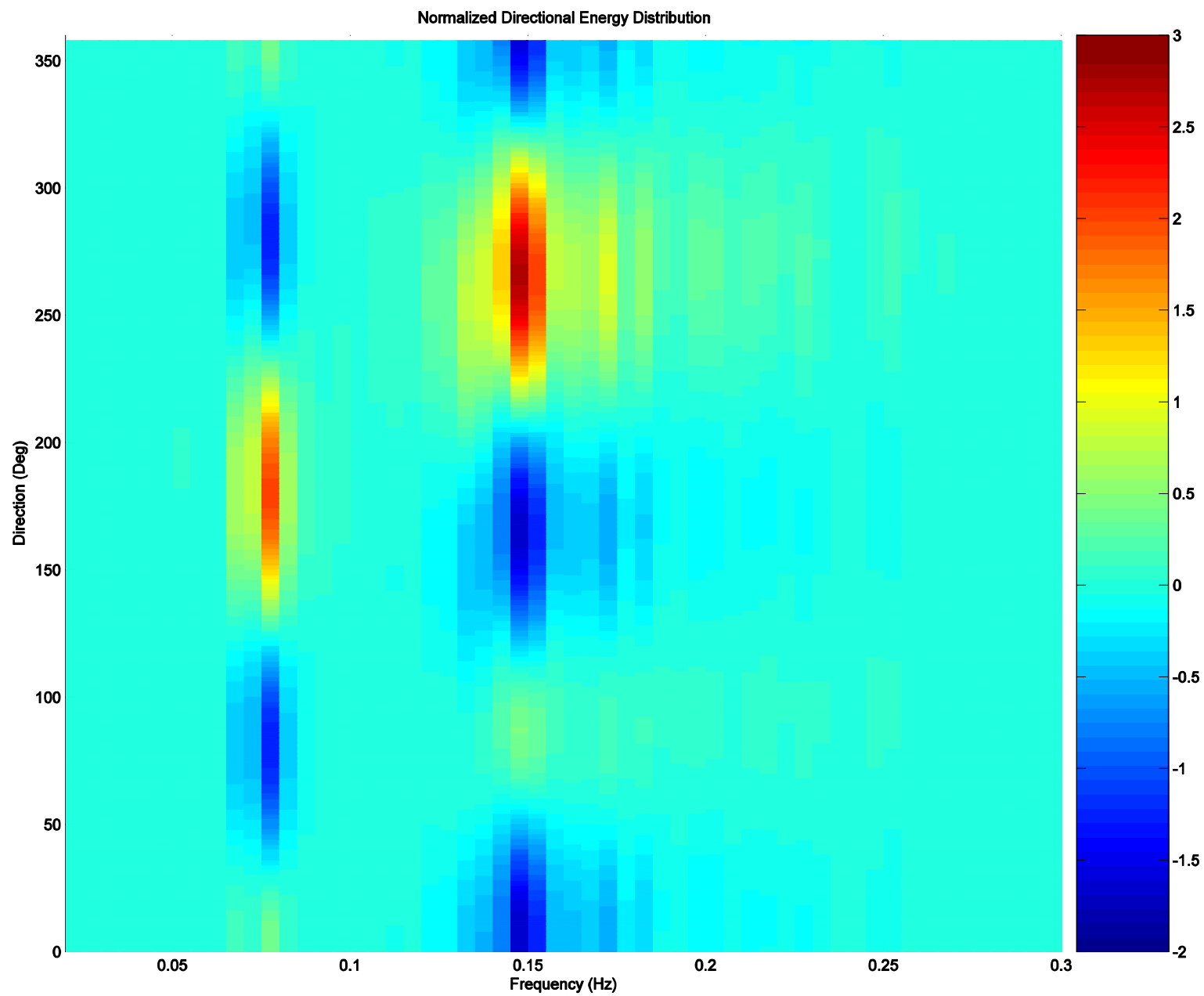
$$D(f, \theta) = \frac{1}{\pi} \left[\frac{1}{2} + \sum_n \{a_n \cos n\theta + b_n \sin n\theta\} \right]$$

Longhuet-Higgins 1963

Approximated by first 4 Fourier coefficients derived from various power spectra from directional measures, ie PUV

Problem with negative energy

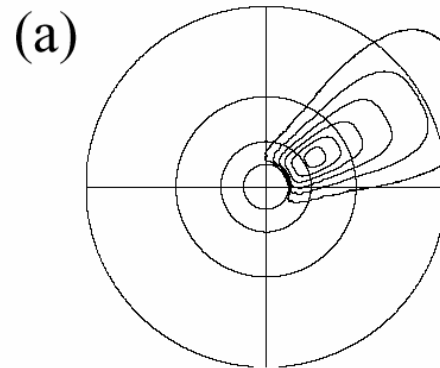
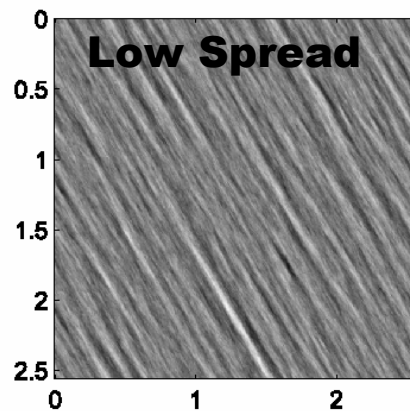
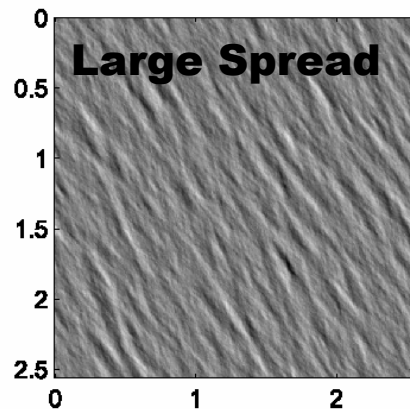
Therefore several methods followed including, Maximum Entropy and Parametric models.





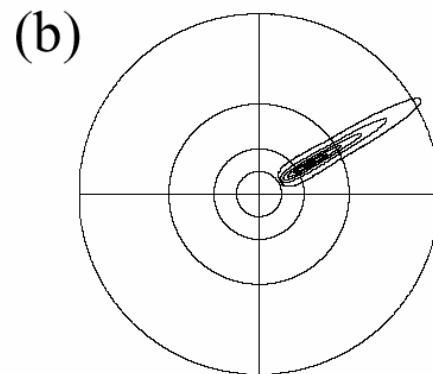
Directional Wave Estimates

$$D(f, \theta) = \frac{1}{\pi} \left[\frac{1}{2} + \sum_n \{a_n \cos n\theta + b_n \sin n\theta\} \right]$$



Mean direction

$$\theta_1(f) = \arctan(b_1(f)/a_1(f))$$



Spreading (directional variance)

$$\sigma = \sqrt{2(1-r_1)}$$

$$r_1 = \sqrt{a_1^2 + b_1^2}$$



A Brief History of Bottom Mounted Wave Measurements

PUV (1970's)

Dramatic attenuation: limited long waves and Coastal waters.

Doppler Profiler (mid 1980's)

Near surface current measurements:

Roughly doubles deployment depth but still depth limited

By projected array size.

Directional measurements with AST (2002)

Essentially removed the depth limit for nondirectional (H_s T_p)

However directional "array" limit remains.

SUV (2005)

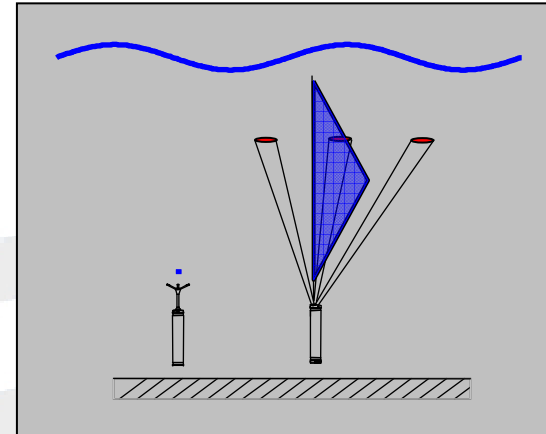
Possibility for subsurface buoy mount

New directional solution based on direct measurements



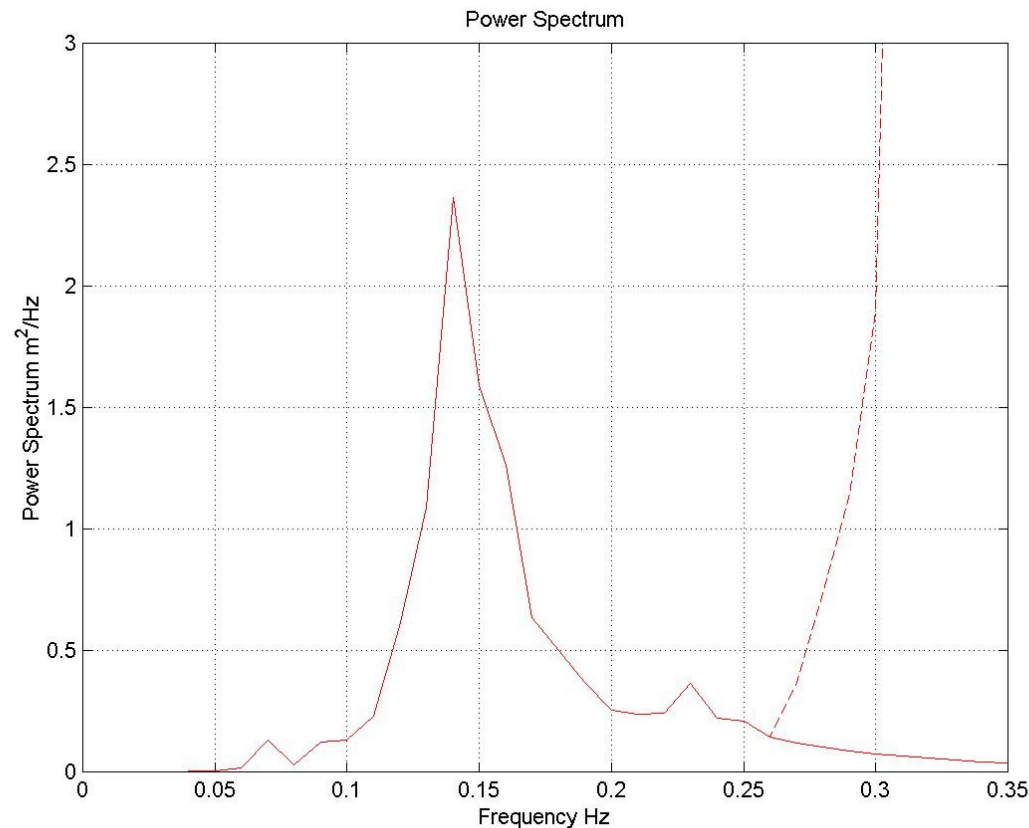
PUV Method

- **Aquadopp, Vector or Aquapro**
- **Measures Pressure and Horz Velocity (U and V)**
- **Out of Harms way**
- **Can collect data for months or days**
- **Straight forward Solution**
- **Applicable for Depths < 20 m**
- **Inferred solution**





Extrapolating Spectra

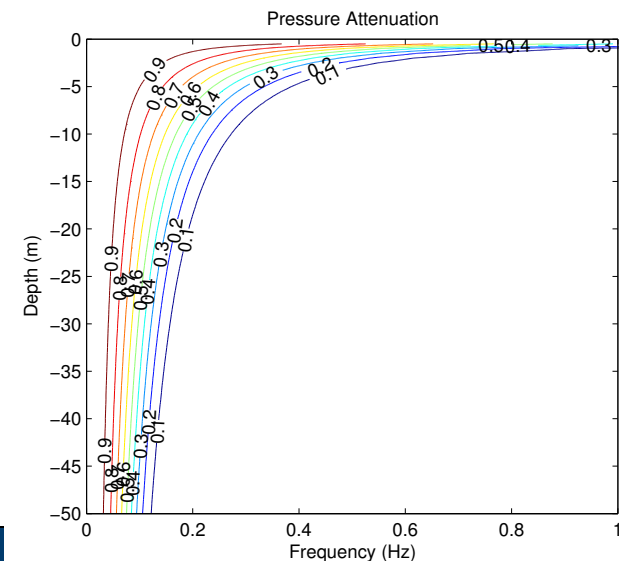


Apply Transfer Function to arrive at Power Spectra for Surface Elevation

Quality control spectra via smoothing and extrapolating beyond cutoff freq

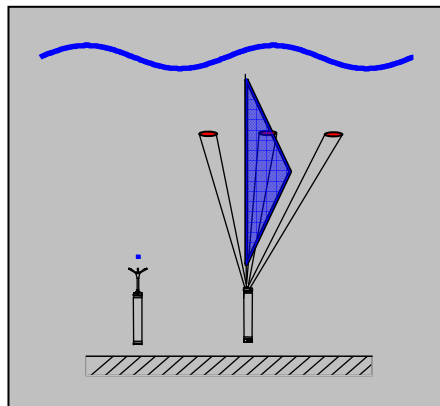
Use Power Spectra to Estimate Statistical Parameters (H_s , T_p)

$$S(f) = P(f)^2 / T(f)^2$$





Estimated PUV Performance

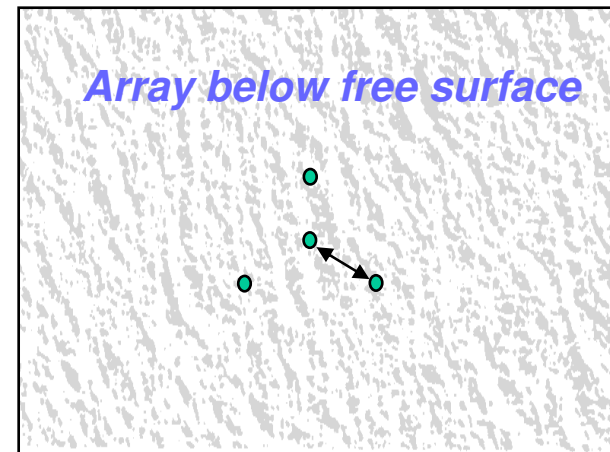
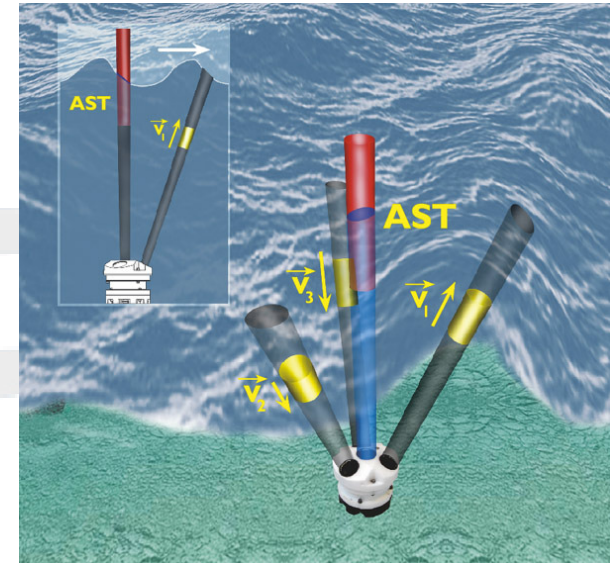


Depth	Period	Hs
20	5.8	0.75
20	6.4	0.60
20	7.2	0.35
20	8.3	0.30
20	10.1	0.20
15	5.0	0.50
15	5.5	0.40
15	6.2	0.25
15	7.1	0.20
15	8.7	0.15
10	4.1	0.40
10	4.5	0.30
10	5.0	0.20
10	5.8	0.15
10	7.1	0.10
5	2.9	0.20
5	3.2	0.15
5	3.6	0.10
5	4.1	0.07
5	5.0	0.05
3	2.3	0.12
3	2.5	0.10
3	2.8	0.05
3	3.2	0.04
3	3.9	0.03



AWAC: Waves and Current Profiles In one instrument

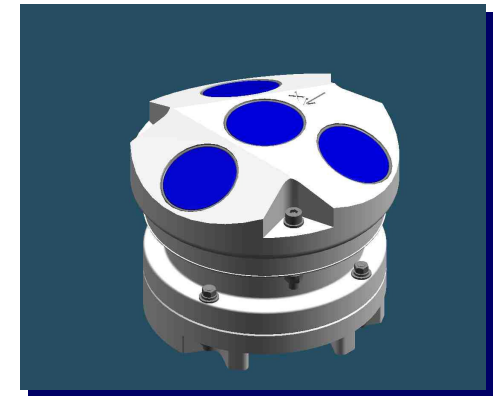
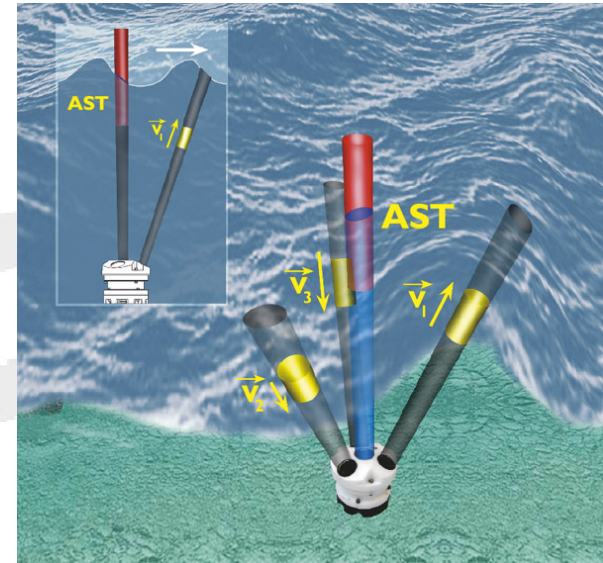
- Alternating Profile/Wave modes
- Projects and "Array" just below the surface
- Special wave processing: Maximum Likelihood Method
- Nondirectional solution is coupled to the Directional solution





AWAC: Waves and Current Profiles In one instrument

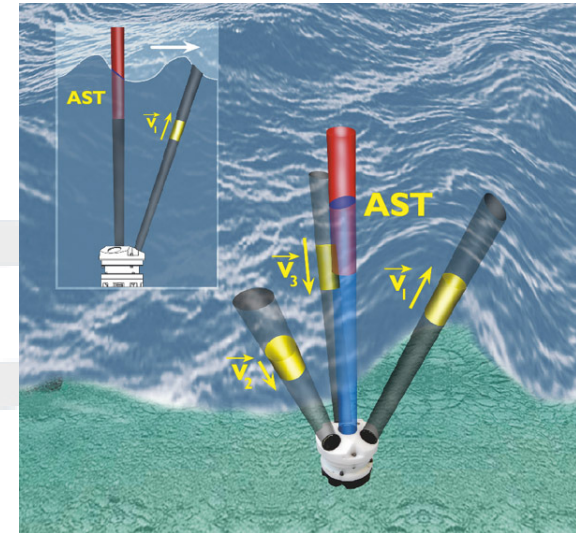
- 1 MHz or 600 kHz Transmit
- Measure current profile 25/50 m range
- Wave measurements 35/60 m range
- Sample at 2 Hz (or 4 Hz 1 MHz only)
- Self-contained w/ internal recorder & batteries
1 burst/hour setup provides 6 weeks for 1 battery pack, 26 Mb
- Online data collection (cable, GSM, radio,
Internal Processor, acoustic modem)





Maximum Likelihood Method ... In short

- MLM is a general method for solving directional wave spectra for a spatial array
- Use time-lags between array measurements to estimate directional distribution
- Transfer function for each velocity measurement is directionally dependent

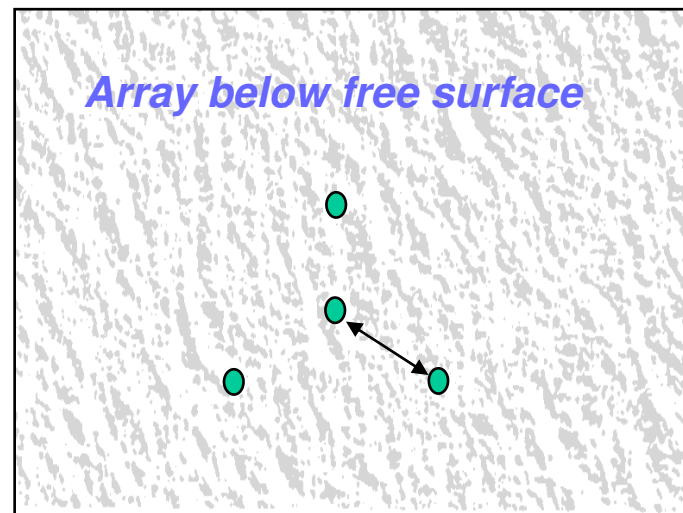


$$D(f, \theta) = \frac{\kappa}{H(f, \theta)^{*t} \Phi(f)^{-1} H(f, \theta)}$$

H = Transfer function

Φ = Cross Spectra

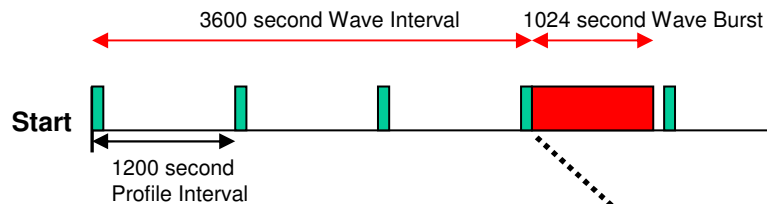
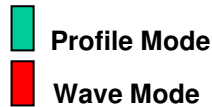
κ = Normalization constant





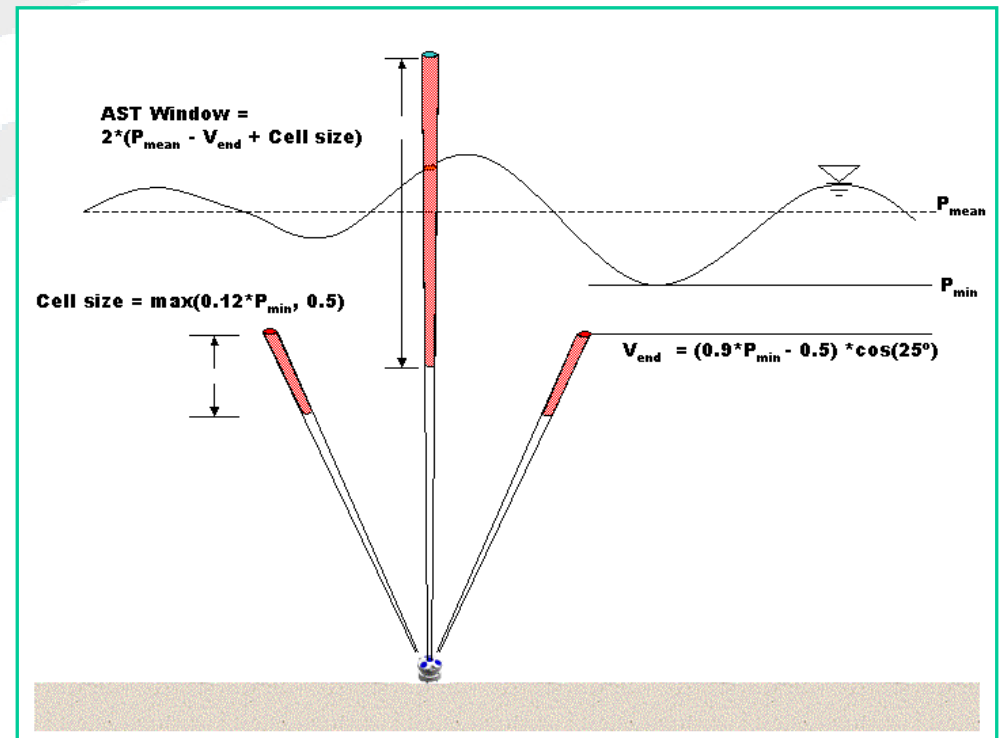
Adaptive Measurement Volumes

Measurement Intervals



Current Profile:

1. AST Window
2. Cell size
3. Cell position
4. SNR test





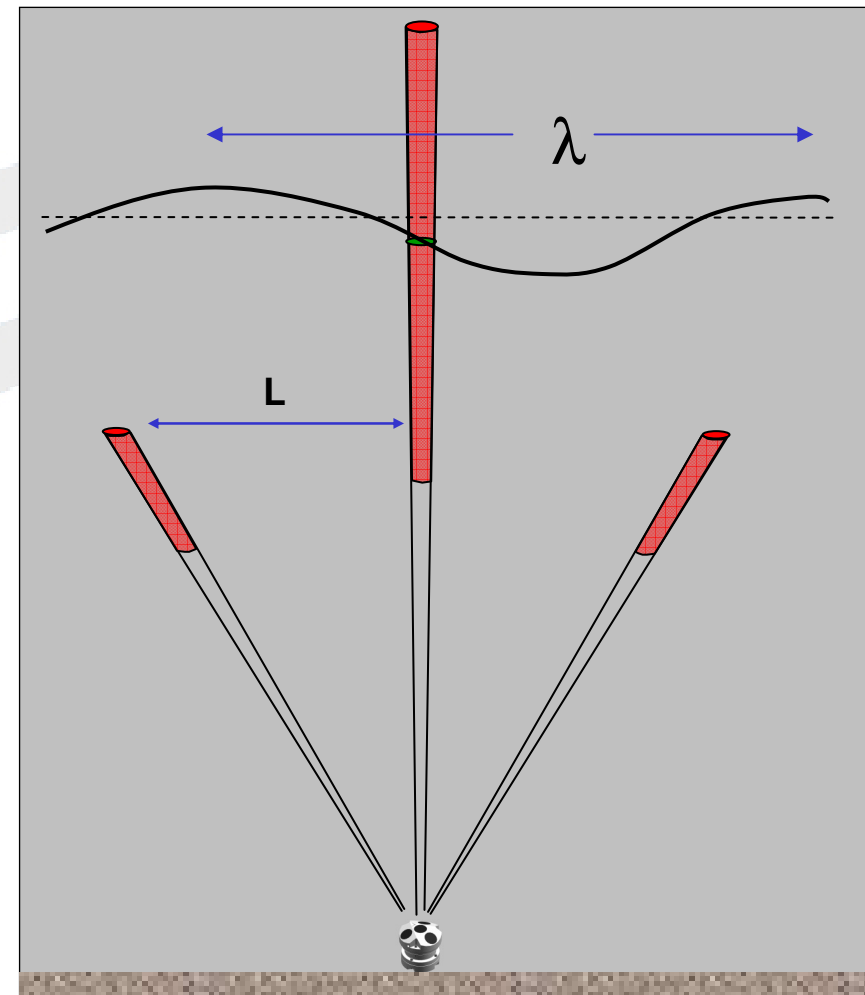
Depth Limited Array

$$L < \lambda/2$$

Geometric limitation

**Measurement cell separation
must be less than half wavelength**

**Separation increases for greater
Depths**



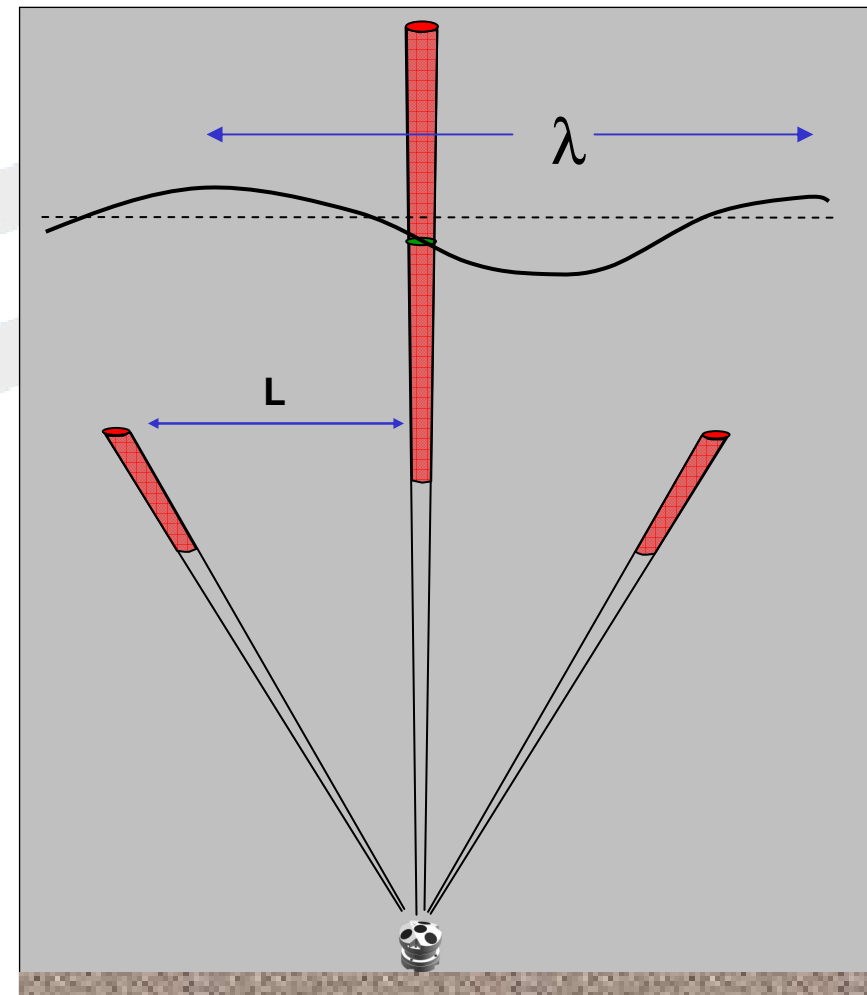


Depth Limited Array

Depth	Cutoff Freq	Cutoff Period
5	0.7	1.45
10	0.45	2.20
20	0.32	3.10
30	0.26	3.85
40	0.23	4.35
50	0.20	5.0
60	0.18	5.55

❖ **Non-directional solution
coupled to directional solution**

$$L < \lambda/2$$





End of Intro

